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Briefing Charts

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Investigation of Optimal Numerical Methods for High Reynolds Number Unsteady Simulations

Ayaboe Edoh, Ann Karagozian, Charles Merkle (Purdue U.), Venkateswaran Sankaran (AFRL)

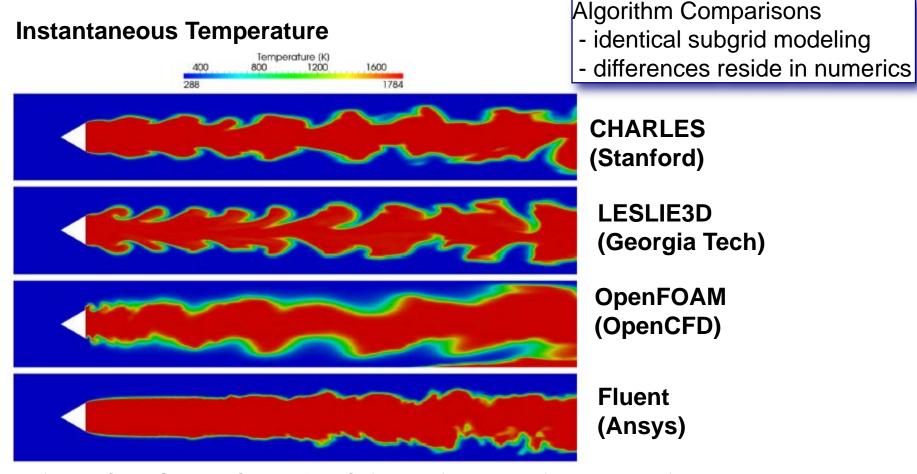


8th SoCal Symposium on Flow Physics
April 12, 2014





Motivation: Large-Eddy Simulation (LES) Challenges



Ref: 2013 - Cocks, Sankaran, Soteriou, "Is LES of reacting flow predictive? Part 1: Impact of Numerics"

Need to determine **BEST** discretization scheme for Reacting LES

Approach

- Investigate dissipation and dispersion characteristics of schemes
 - tied to solution accuracy
 - use Von Neumann Stability Analysis

- Schemes to investigate:
 - Standard Collocated Grid
 - Standard Staggered Grid
 - Kinetic Energy Preserving
 - Collocated & Staggered

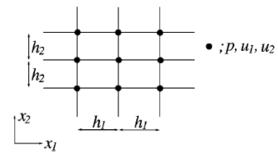


FIG. 1. Regular grid system.

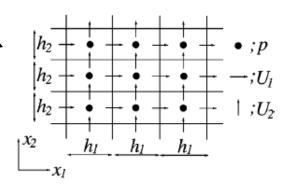


FIG. 2. Staggered grid system.

Von Neumann Analysis

$$\frac{\partial Q}{\partial t} + \frac{\partial E}{\partial x} = 0 \quad \text{1D Euler Eqns} \quad \longrightarrow \quad \frac{\partial Q}{\partial t} + A \frac{\partial Q}{\partial x} = 0 \quad \text{with } A = \partial E / \partial Q$$

Eigenvalues of the amplification matrix specify growth factor and phase errors.

$$Q^{n+1} = GQ^n$$

Staggered Grid Scheme/ Quasi-Linear Form

$$\frac{\Gamma_{ce} \left(\frac{\partial Q_{pT}}{\partial t} + \frac{\partial Q_u}{\partial t} \right)_i}{\partial t} + \Gamma_m \left(\frac{\partial Q_{pT}}{\partial t} + \frac{\partial Q_u}{\partial t} \right)_{i+1/2} + \frac{A_{ce} \left(\frac{\partial Q_{pT}}{\partial x} + \frac{\partial Q_u}{\partial x} \right)_i}{\partial t} + A_m \left(\frac{\partial Q_{pT}}{\partial x} + \frac{\partial Q_u}{\partial x} \right)_{i+1/2} = 0$$



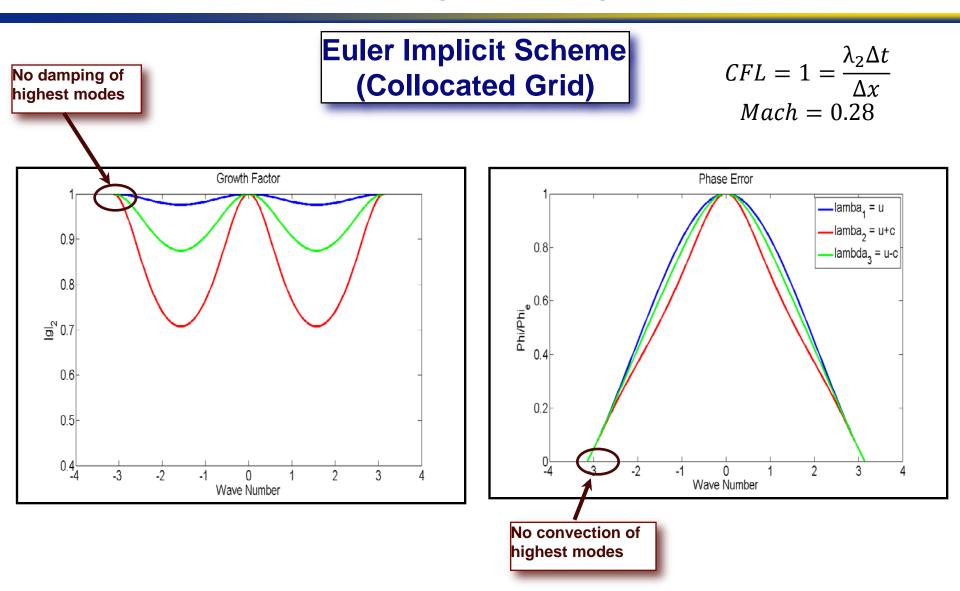
Growth Factor

$$||g_i||$$

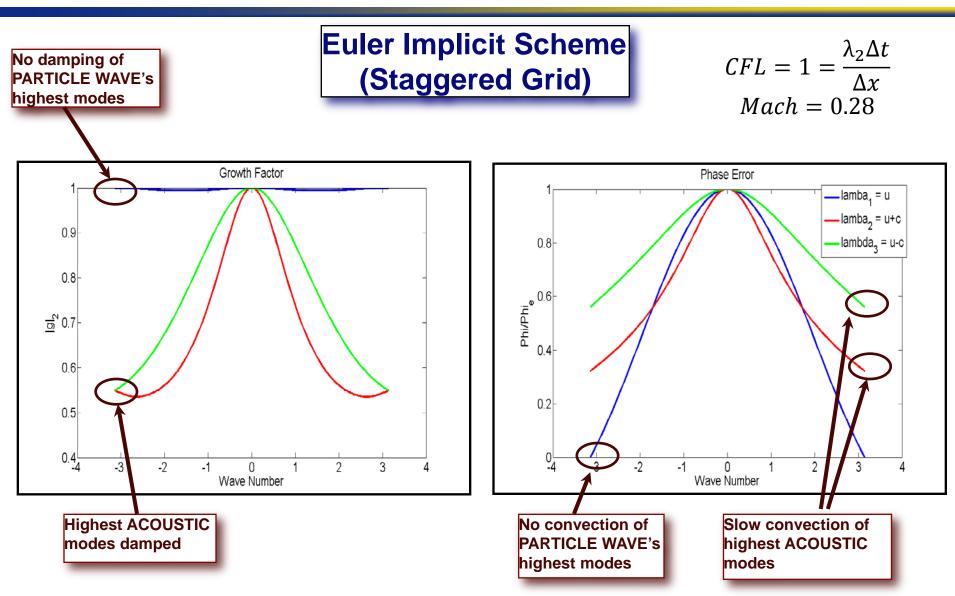
Phase Error

$$\frac{\phi}{\phi_{exact}} = \frac{-\tan^{-1}\{Imag(g_i)/Re(g_i)\}}{CFL \times \beta}$$

Stability Analysis



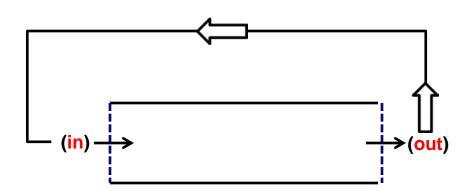
Stability Analysis



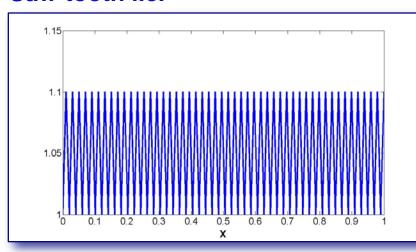
Test Cases

1D Duct

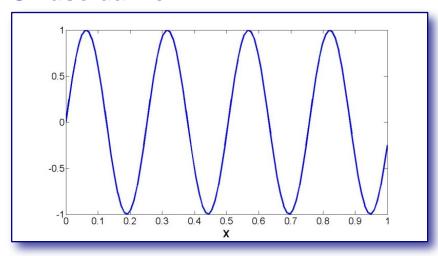
- Periodic BC's



Saw-tooth i.c.



Sinusoidal i.c.



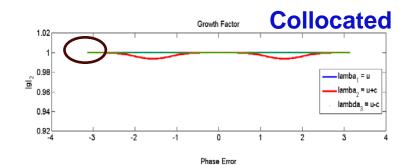
Particle Wave High Frequency Behavior

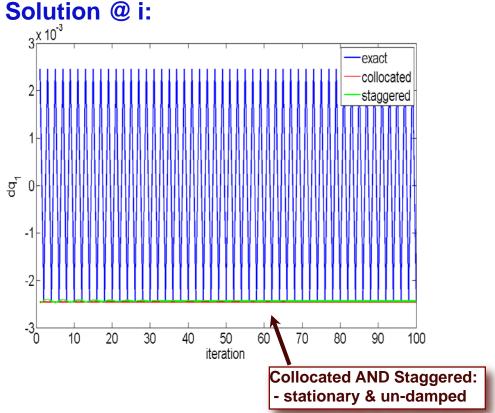
Runge Kutta Scheme

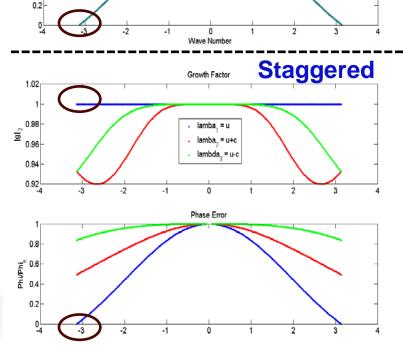
$$CFL = 1 = \frac{\lambda_2 \Delta t}{\Delta x}$$

$$Mach = 0.28$$

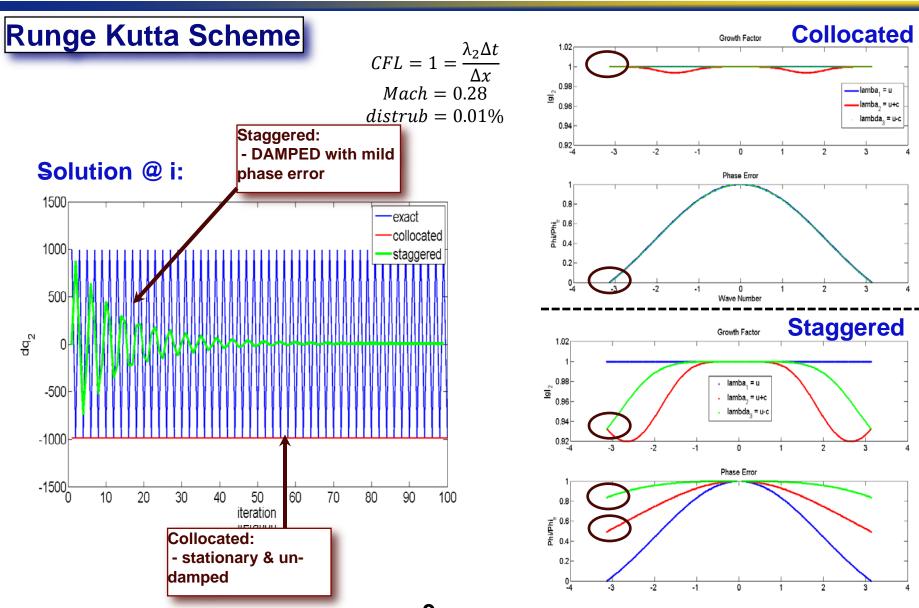
$$distrub = 0.01\%$$







Acoustic Wave High Frequency Behavior



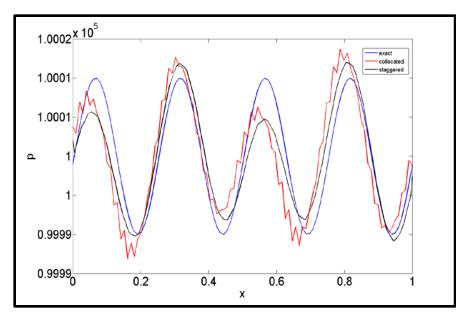
Effect of Boundary Conditions

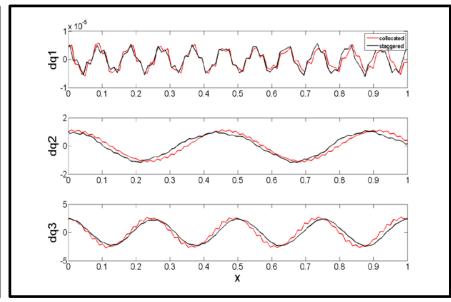
$$CFL = 1 = \frac{\lambda_2 \Delta t}{\Delta x}$$

$$Mach = 0.28$$

$$distrub = 0.01\%$$

$$\begin{aligned} &\Omega + [\Delta \hat{q}_{bc} - \Delta \hat{q}_{int}] = 0 \\ &\Omega_{inlet} = \begin{bmatrix} \rho u - \dot{m}_{in} \\ T - T_{in} \\ 0 \end{bmatrix}, \Omega_{outlet} = \begin{bmatrix} 0 \\ 0 \\ p - p_{out} \end{bmatrix} \end{aligned}$$





Pressure at 10T₃

characteristic variables at 10T₃

high frequency in Collocated pressure solution
 lack of acoustic damping

Kinetic Energy Preservation (KEP)

- "in computations of turbulent flow fields, dissipative errors show up at the level of kinetic energy" (Mahesh 2004)
- Robust at inviscid limit (Re $\rightarrow \infty$)

Incompressible Flow:

$$u_{i} \left\{ \frac{\partial u_{i}}{\partial t} + \frac{\partial u_{i}u_{j}}{\partial x_{j}} = \frac{1}{\rho} \left(-\frac{\partial P}{\partial x_{i}} + \frac{\partial \tau_{ij}}{\partial x_{j}} \right) \right\} \xrightarrow{\frac{\partial u_{j}}{\partial x_{j}}} \frac{\partial}{\partial t} \left(\frac{1}{2} u_{i}^{2} \right) + \frac{\partial}{\partial x_{j}} \left(\frac{1}{2} u_{i}^{2} u_{j} \right) = \frac{1}{\rho} \left(-\frac{\partial u_{i}P}{\partial x_{i}} + u_{i} \frac{\partial \tau_{ij}}{\partial x_{j}} \right)$$

- K = ½ u_i² bounded and constant at inviscid limit
 KEP schemes satisfy secondary equation discretely
 Richtmeyer & Morton (1967)
- Arakawa (1966)

Compressible Flow:

$$\frac{-u_{i}^{2}}{2} \left\{ \frac{\partial}{\partial t} \rho + \frac{\partial}{\partial x_{j}} \rho u_{j} \right\} + u_{i} \left\{ \frac{\partial}{\partial t} \rho u_{i} + \frac{\partial}{\partial x_{j}} \rho u_{i} u_{j} + \frac{\partial}{\partial x_{i}} P - \frac{\partial}{\partial x_{j}} \tau_{ij} \right\} = 0$$

$$\frac{\partial}{\partial t} \left(\frac{1}{2} \rho u_{i}^{2} \right) + \frac{\partial}{\partial x_{j}} \left(\rho u_{j} \frac{u_{i}^{2}}{2} \right) = \frac{1}{\rho} \left(-u_{i} \frac{\partial P}{\partial x_{i}} + u_{i} \frac{\partial \tau_{ij}}{\partial x_{j}} \right)$$

- Discrete analogue seeks:
 - Accurate transport of KE →accurate physical transfer of energy: E = KE + U_{int}

KEP: Applied to 1D Euler

(Collocated Grid)

- compare Crank-Nicolson (CN) with Fully KEP scheme (F-KEP)

$$\frac{(\rho \phi_{k})_{i}^{n+1} - (\rho \phi_{k})_{i}^{n}}{\Delta t} + \frac{1}{V_{i}} \sum_{f} (\phi)_{f}^{m} (\rho \mathbf{u}_{j})_{f}^{n+1/2} \cdot S_{i} + \frac{1}{V_{i}} \sum_{f} \left(\frac{\partial p v_{k,j}}{\partial x_{j}} \right)_{f}^{n+1/2} \cdot S_{i} = 0$$

$$\phi^{m} = \frac{1}{2}(\phi^{n+1} + \phi^{n}) \qquad \phi^{m} = \frac{(\sqrt{\rho}\phi)^{n+1} + (\sqrt{\rho}\phi)^{n}}{(\sqrt{\rho})^{n+1} + (\sqrt{\rho})^{n}}$$
(CN)
(F-KEP)

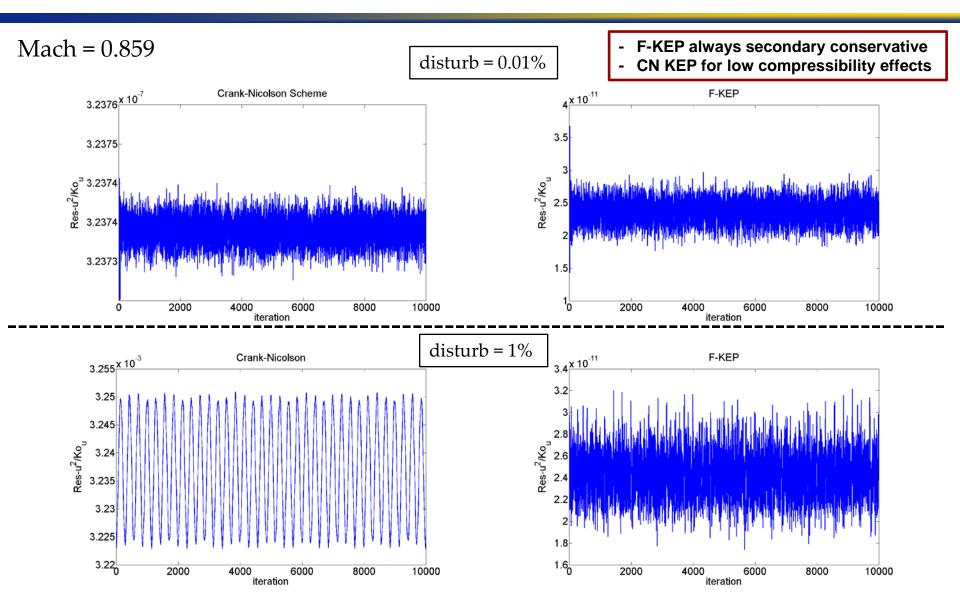
Subbareddy/Candler(2009)
Merkle (2013)

$$\phi = \begin{bmatrix} 1 \\ u \\ e \\ Y_k \end{bmatrix}$$

- discrete secondary equation satisfied to machine zero if KEP

$$\frac{(\rho\phi_{k}^{2})_{i}^{n+1} - (\rho\phi_{k}^{2})_{i}^{n}}{2\Delta t} + \frac{1}{V_{i}} \sum_{f} (\rho u_{j}^{n+1/2})_{f} \left(\frac{\phi_{k}^{2}}{2}\right)_{f}^{m} \cdot S_{f,i} + \phi_{k,i}^{m} \frac{1}{V_{i}} \sum_{f} (\rho v_{k,j})^{n+1/2} \cdot S_{f,i} = RESIDUAL$$
with
$$\left(\frac{\phi_{k}^{2}}{2}\right)_{f}^{m} = \frac{1}{2} \left(\frac{\phi_{k}}{2}\right)_{i}^{m} \left(\frac{\phi_{k}}{2}\right)_{nbr}^{m}$$

Evaluating KEP: u²



Going Forward

Key Questions:

- What is the advantage of kinetic energy preservation for LES?
- Does it help minimize or eliminate the need for artificial dissipation?
- What about the relative importance of dispersion errors?
- Implement Merkle's generalized KEP schemes
 - Formulated for both staggered and collocated schemes
 - Major advantage is that it is KE preserving for the scalar transport as well
 - Can we minimize or eliminate the need for artificial dissipation for scalars?
- Extend schemes to multi-dimensional code
 - Apply to non-reacting and reacting LES computations

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